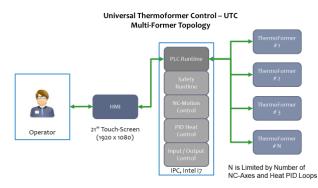
AUTOMATION CONTROL SOURCE

The UTC, or Universal Thermoformer Control from Automation Control Source, is a pre-engineered, modular, open, white branded control platform for Machine Builders. The UTC has been designed to cost efficiently run any Thermoforming Equipment, regardless of material, heating/forming/trimming sequence, and is available as a standalone or multi machine control option.

The UTC integrates the latest in both industrial control technology hardware and software, it uses only standardized programming function blocks.

As an open solution the UTC is capable of controlling any legacy analog servo drive/motor package, as well as the latest available in digital servo drives/motors with Fieldbus interface. All without requiring you to change your PLC program.



By providing an abstraction layer between the Control

Program and the attached hardware, your machine control is freed from the legacy "control-hardware-vendor lock-in". You'll no longer have to worry about having to use obsolete and expensive OEM components.

Everything you need to control your thermoforming equipment is included, whether it be your first machine or your next generation of equipment. With a spectacular 21.5" panel mount or standalone HMI multi-touch screen, the operator has full control over the machine recipe, temperature, feeding, forming and trimming; including precise process-triggers. The HMI design is modern and very intuitive, minimizing the learning curve for your operators.

The UTC platform from Automation Control Source is worry free and easy to maintain, as all of the machine parameters and configurations are controller based. This makes the replacing of individual machine control components a breeze. The UTC's open architecture also allows for seamless integration into existing SCADA, OPC UA, or any other IOT reporting or analytics platform.



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UTC CONFIGURATIONS AND TECHNICAL SPECIFICATIONS:

| DESCRIPTION OF FEATURES | SINGLE MACHINE CONTROL | MULTIPLE MACHINE CONTROL |
|----------------------------------|---------------------------------|---------------------------------|
| НМІ | | |
| Panel Mount Model | Beckhoff CP2921 | Beckhoff CP2921 |
| Standalone Model | Beckhoff CP3921 | Beckhoff CP3921 |
| Size | 21.5″ | 21.5" |
| Resolution | 1920 x 1080, HD | 1920 x 1080, HD |
| Touchscreen | Multitouch | Multitouch |
| Development | < 4000 Tags | < 16000 Tags |
| Embedded Industrial PC | | |
| Model | Beckhoff CX2020 | Beckhoff CX2040 |
| Processor | Intel Celeron 1.4 GHz, 1 Core | INTEL I7 2.1GHz, 4 Cores |
| Operating System | Win7 Standard Embedded or | Win7 Standard Embedded or |
| | Win10 IOT, 32 or 64 Bit | Win10 IOT, 32 or 64 Bit |
| RAM, SSD | 2 GB DD3 RAM, 8 GB CFast | 4 GB DD3 RAM, 8 GB CFast Card |
| | Card | |
| Safety PLC Module | Beckhoff EL-6900 | Beckhoff EL-6900 |
| Performance (Recommended | | |
| Limits) | | |
| PLC Runtimes (Minimum 1ms Cycle) | 1 | 4 |
| NC-Tasks (Motion Axis) | < 10 | < 50 |
| PID-Heat Control Loops | < 50 | < 250 |
| Digital and Analog I/O | < 350 | < 2000 |
| (EL-Type Modules preferred, not | | |
| included) | | |
| Supported Motor Drive Interfaces | | |
| Analog | 0-10V, -10-+10V, 4-20mA | 0-10V, -10-+10V, 4-20mA |
| Digital | Step/Direction, PWM, Fieldbus | Step/Direction, PWM, Fieldbus |
| Fieldbus Protocols* | EtherCAT, Ethernet, Profibus, | EtherCAT, Ethernet, Profibus, |
| | Profinet, Ethernet/IP, | Profinet, Ethernet/IP, CANopen, |
| | CANopen, Sercos, CC-Link, | Sercos, CC-Link, Modbus, |
| *(EtherCAT and 1 other included) | Modbus, RS232/485 and many | RS232/485 and many others |
| | others | |
| Servo Control Type | Position, Velocity or both | Position, Velocity or both |
| Encoder Feedback | Incremental/SinCos, RS422, | Incremental/SinCos, RS422, SSI, |
| | SSI, EnDAT2.2, BISS or Fieldbus | EnDAT2.2, BISS or Fieldbus |
| Lifetime Licenses (Included) | | |
| HMI Runtime License | 4000 Tags | 16000 Tags |
| TC3, PLC, NC-PTP and Temperature | Performance Plus (50) | High Performance (70) |
| Controller Runtime Licenses | | |
| Pricing | | |
| UTC Control Runtime | Upon request | Upon request |

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